The Normal Distribution

BIOS 6611

CU Anschutz

Week 3

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Welcome to the Rest of Your Life!

Source: The Good Place

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The **normal distribution** (also called the Gaussian distribution) is one of the most important distributions in statistics

The normal distribution has unique properties that make it extraordinary:

- **•** the central limit theorem
- the linear combination of normally distributed random variables is still normal
- it isn't terrible to work with mathematically

The PDF of the normal distribution is defined by two parameters:

- **●** μ is the *mean* and represents the "location"
- σ^2 is the *variance* and represents the "squared scale", where $\sigma^2 > 0$

The probability density function is

$$
f(x) = \frac{1}{\sigma\sqrt{2\pi}}\exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right), \ -\infty < x < \infty
$$

From the PDF we could prove that $E(X) = \mu$ and $Var(X) = \sigma^2$ for the normal distribution

Normal Properties - I

The normal distribution is symmetric about μ (i.e., $f(\mu + x) = f(\mu - x)$):

Normal Properties - II

This symmetry also helps with some quick rules of thumb for probability:

•
$$
P(\mu - \sigma < X < \mu + \sigma) = 0.6827
$$
 (about 68% lies between ± 1 s.d.)

- P(*µ* − 2*σ <* X *< µ* + 2*σ*) = 0*.*9545 (about 95% lies between ±2 s.d.)
- P(*µ* − 3*σ <* X *< µ* + 3*σ*) = 0*.*9973 (about 99.7% lies between ±3 s.d.)

Normal Properties - III

The symmetry of the normal distribution also means that all three common summaries of central tendency (i.e., the mean, median, and mode) are all equal to *µ*

Quick Review:

- mean: the (arithmetic) average of our sample
- **•** median: the middle value of our sample when arranged in order of magnitude (i.e., smallest to largest)
- mode: the most frequent value of our sample (i.e., the peak of the PDF)

The PDF Shape with Varying *σ* 2

Normal Random Variable

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The simplest form of the normal distribution is when $\mu=0$ and $\sigma^2=1$: X ∼ N(0*,* 1). This is called the **standard normal distribution**.

The PDF for the standard normal distribution is

$$
f(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}x^2\right), -\infty < x < \infty
$$

Here the PDF is simpler than the general form we saw earlier, where we now have $E(X) = 0$ and $Var(X) = 1$.

We can transform any normally distributed random variable (e.g., $X \sim {\mathsf N}(\mu,\sigma^2))$ in a standard normal variable (e.g., $Z \sim {\mathsf N}(0,1))$:

$$
Z=\frac{X-\mu}{\sigma}
$$

Because the standard normal distribution is utilized so frequently, its PDF and CDF have special notation:

- *φ*(z) is our standard normal PDF
- $\Phi(z)$ is the standard normal CDF

Φ(z) **of Yesteryear**

T-2 Tables

TABLE A

Standard Normal probabilities

 2.2 .02.1 (20 N.00) .0139 .0129 .0129 .0129 .0129 .0129 .0129 .0125 .0123 .01

Φ(z) **(and more) of Today**

Fortunately, we don't have to only rely on tables today. In R we can calculate the PDF $(\phi(z))$ with dnorm(), CDF $(\Phi(z))$ with pnorm(), or the value z is for a given area under the curve (AUC) with $qnorm()$:

z <- **-**2.58 **dnorm**(z) *#PDF*

[1] 0.01430511

pnorm(z) *#CDF*

[1] 0.004940016

qnorm(0.004940016) *#quantile (i.e., z-score for a given AUC)*

 $\#$ \uparrow \uparrow

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Standard Normal PDF

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Population Moments

So far we have discussed location and variability of distributions, but we can also describe the **skewness** and **kurtosis** of the population (or a sample also).

 $E(X) = \mu$ and $E(X^2)$ are population moments about zero.

 $E[(X - \mu)] = 0$ and $E[(X - \mu)^2] = \sigma^2$ are population moments about μ (these are also called central moments).

From the central moments we can represent the standardized moments by dividing the k^{th} standard deviation:

\n- \n
$$
\frac{E\left[\left(X-\mu\right)^3\right]}{\sigma^3}
$$
 represents the skewness\n
\n- \n $\frac{E\left[\left(X-\mu\right)^4\right]}{\sigma^4}$ represents the kurtosis\n
\n

Skewness

Skewness describes the symmetry of the distribution.

- The 3rd central moment of the data, like the 1st, will balance out from left to right if the data are symmetric.
- With normally distributed data, we expect skewness to be 0 (i.e., balanced).
- \bullet If skewness is >0 : positive skew; skewed to the right; more common
- \bullet If skewness is $\lt 0$: negative skew; skewed to the left

Kurtosis

Kurtosis describes the "tailedness" of the probability distribution. Often we are interested in the **excess kurtosis**, which is Kurt[X] - 3.

- Excess Kurtosis $= 0$, tails just like a normal distribution (mesokurtic); such as the normal distribution and binomial when $\rho=\frac{1}{2}\pm\sqrt{\frac{1}{12}}$ 12
- Excess Kurtosis > 0 , heavier/fatter tails than a normal distribution (leptokurtic); such as Student's t, exponential, and Poisson distributions
- Excess Kurtosis < 0 , lighter/thinner tails than a normal distribution (platykurtic); such as uniform and Bernoulli distributions

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Some people prefer specifying the scale of then normal distribution in terms of its **precision** instead of the variance

The precision is the reciprocal of the variance: $\tau = \frac{1}{\sigma^2}$

The PDF in this parameterization is

$$
f(x) = \sqrt{\frac{\tau}{2\pi}} \exp\left(-\frac{\tau(x-\mu)^2}{2}\right), \ -\infty < x < \infty
$$

One of the more common places you will see this parameterization is with Bayesian statistics